

The B Modelling Language

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B is a modelling language

- ◇ B is used for modelling closed systems
 - ◇ B is not a programming language but a language for developing **models of systems**
 - ◇ A B model is defined by a set of **events**
 - ◇ A B model is characterized by an **invariant**
 - ◇ A B model states safety properties of the current system
 - ◇ A B model is internally consistent with respect to a list of **proof obligations**
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Events System Models

An **event system model** is made of

State **constants** and state **variables** constrained by a state **invariant**

A finite set of **events**

Proofs ensures the consistency between the invariant and the events

An event system model can be **refined**

Proofs must ensure the correctness of refinement

B models

MODEL

m

SETS

s

CONSTANTS

c

PROPERTIES

$P(s, c)$

VARIABLES

x

INVARIANT

$I(x)$

ASSERTIONS

$A(x)$

INITIALISATION

<substitution>

EVENTS

<list of events>

END

- ✓ A model has a **name** m
- ✓ the clause **SETS**, **CONSTANTS** and the clause **PROPERTIES** introduce information related to the **mathematical structure of the problem** to solve
- ✓ The invariant $I(x)$ types the variable x , which is assumed to be initialized with respect to the initial conditions and which is preserved by events (or transitions) of the list of events.

Meaning of the B model

- ◇ s , c and $P(s, c)$ define the mathematical structure of the problem: $\Gamma(s, c)$.
 - ◇ Each computation starts by a state satisfying $Init(x)$.
 - ◇ The list of possible events is $\{e_1, \dots, e_n\}$ and any event e is characterized by a binary relation $BA(e)(x, x')$ over possible values of x .
 - ◇ For each event e , there is a condition called a guard which is true, when the event is observed.
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Events

Event: E	Before-After Predicate
BEGIN $x : P(x_0, x)$ END	$P(x, x')$
SELECT $G(x)$ THEN $x : P(x_0, x)$ END	$G(x) \wedge P(x, x')$
ANY t WHERE $G(t, x)$ THEN $x : P(x_0, x, t)$ END	$\exists t \cdot (G(t, x) \wedge P(x, x', t))$

Guards of event

Event: E	Guard: $\text{grd}(E)$
BEGIN S END	$TRUE$
SELECT $G(x)$ THEN T END	$G(x)$
ANY t WHERE $G(t, x)$ THEN T END	$\exists t. G(t, x)$

Proof obligations for a B model

	Proof obligation
(INV1)	$\Gamma(s, c) \vdash \text{Init}(x) \Rightarrow I(x)$
(INV2)	$\Gamma(s, c) \vdash I(x) \wedge \text{BA}(e)(x, x') \Rightarrow I(x')$
(DEAD)	$\Gamma(s, c) \vdash I(x) \Rightarrow (\text{grd}(e_1) \vee \dots \vee \text{grd}(e_n))$
(SAFE)	$\Gamma(s, c) \vdash I(x) \Rightarrow A(x)$
(FIS)	$\Gamma(s, c) \vdash I(x) \wedge \text{grd}(E) \Rightarrow \exists x' \cdot P(x, x')$

Modelling systems: Hello world!

MODEL

FACTORIAL_EVENTS

CONSTANTS *factorial, p*

PROPERTIES

$$\begin{aligned} & p \in \mathbb{N} \wedge \text{factorial} \in \mathbb{N} \leftrightarrow \mathbb{N} \wedge 0 \mapsto 1 \in \text{factorial} \wedge \\ & \forall (n, fn). (n \mapsto fn \in \text{factorial} \Rightarrow n+1 \mapsto (n+1) \cdot fn \in \text{factorial}) \wedge \\ & \forall f \cdot \left(\begin{array}{l} f \in \mathbb{N} \leftrightarrow \mathbb{N} \wedge \\ 0 \mapsto 1 \in f \wedge \\ \forall (n, fn). (n \mapsto fn \in f \Rightarrow n+1 \mapsto (n+1) \times fn \in f) \\ \Rightarrow \\ \text{factorial} \subseteq f \end{array} \right) \end{aligned}$$

VARIABLES

result

INVARIANT

result $\in \mathbb{N}$

ASSERTIONS

factorial $\in \mathbb{N} \longrightarrow \mathbb{N}$;

factorial(0) = 1;

$\forall n. (n \in \mathbb{N} \Rightarrow \text{factorial}(n+1) = (n+1) \times \text{factorial}(n))$

INITIALISATION

result := $\in \mathbb{N}$

EVENTS

computation = **BEGIN** *result* := *factorial*(*p*) **END**

END

Modelling systems: communications

SETS

MESSAGES; AGENTS

PROPERTIES

$MESSAGES \neq \emptyset \wedge$

$AGENTS \neq \emptyset$

VARIABLES

sent, got, lost

Modelling systems: communications

INVARIANT

$$sent \subseteq AGENTS \times AGENTS \times MESSAGES \wedge$$

$$got \subseteq AGENTS \times AGENTS \times MESSAGES \wedge$$

$$lost \subseteq AGENTS \times AGENTS \times MESSAGES \wedge$$

$$(got \cup lost) \subseteq sent \wedge$$

$$lost = \emptyset$$

INITIALISATION

$$sent := \emptyset \parallel$$

$$got := \emptyset \parallel$$

$$lost := \emptyset$$

Modelling systems: communications

SENDING =

ANY *agent1, agent2, message* **WHERE**

agent1 ∈ *AGENTS* ∧

agent2 ∈ *AGENTS* ∧

message ∈ *MESSAGES* ∧

agent1 ↦ *agent2* ↦ *message* ∉ *sent*

THEN

sent := *sent* ∪ {*agent1* ↦ *agent2* ↦ *message*}

END;

RECEIVING = **ANY** *agent1, agent2, message* **WHERE**

agent1 ∈ *AGENTS* ∧

agent2 ∈ *AGENTS* ∧

message ∈ *MESSAGES* ∧

agent1 ↦ *agent2* ↦ *message* ∈ *sent* ∧

agent1 ↦ *agent2* ↦ *message* ∉ *got*

THEN

got := *got* ∪ {*agent1* ↦ *agent2* ↦ *message*}

END;

LOOSING = **BEGIN** SKIP **END**

Modelling systems: problems?

- ∅ Systems are generally very complex
- ∅ Invariant should be strong enough for proving safety properties
- ∅ Problems for modelling: finding suitable mathematical structures, listing events or actions of the system, proving proof obligations, ...

Solution: refining models

- ☺ To understand more and more the system
 - ☺ To distribute the complexity of the system
 - ☺ To distribute the difficulties of the proof
 - ☺ To improve explanations
 - ☺ Validation (step by step)
 - ☺ Refinement (invariant & behavior)
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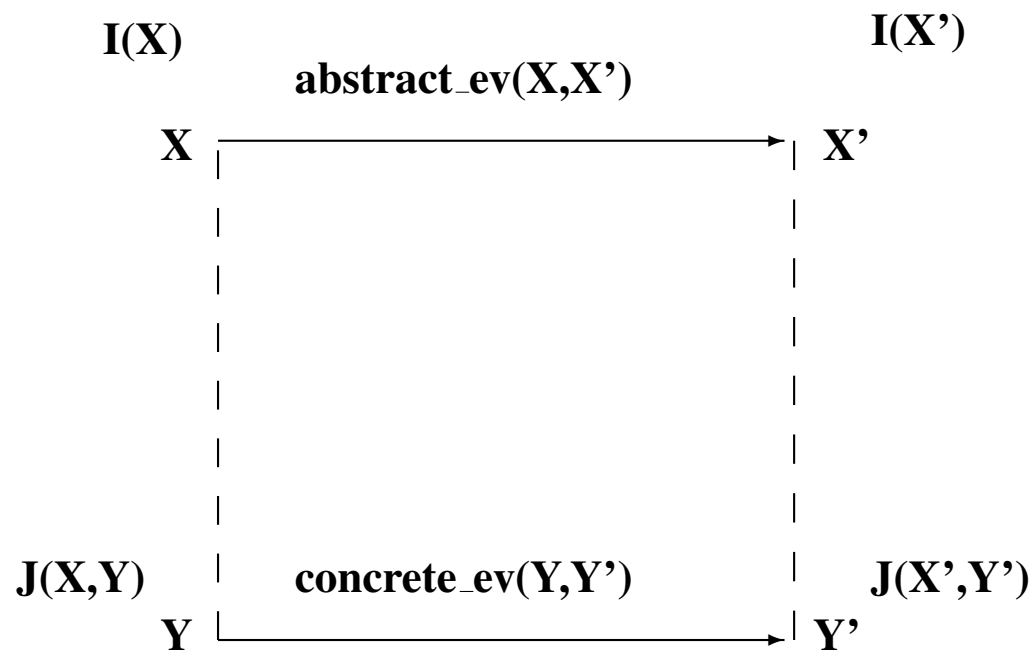
Refinement of models

- ◇ we can add more details (like superposition),
 - ◇ we can add new events (we can observe more transformations),
 - ◇ we prove that the concrete behaviors are abstract ones
 - ◇ \rightsquigarrow we got the abstract invariant for free.
 - ◇ each new event refines **SKIP**
 - ◇ no deadlock
 - ◇ abstract events occur (new events decrease something)
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Refinement

```
REFINEMENT  $r$   
REFINES  $m$   
SETS  $t$   
CONSTANTS  $d$   
PROPERTIES  $Q(t, d)$   
VARIABLES  $y$   
INVARIANT  
   $J(x, y)$   
VARIANT  
   $V(y)$   
ASSERTIONS  
   $B(y)$   
INITIALISATION  
   $y : INIT(y)$   
EVENTS  
  <list of events>  
END
```


Refinement of a model by another one



Proof obligations for refinement

(REF1) $\text{INITC}(y) \Rightarrow \exists x.(\text{INIT}(x) \wedge \text{J}(x, y)) :$

The initial condition of the refinement model imply that there exists an abstract value in the abstract model such that that value satisfies the initial conditions of the abstract one and implies the new invariant of the refinement model.

(REF2) $\text{I}(x) \wedge \text{J}(x, y) \wedge \text{BAC}(y, y') \Rightarrow \exists x'.(\text{BAA}(x, x') \wedge \text{J}(x', y')) :$

The invariant in the refinement model is preserved by the refined event and the activation of the refined event triggers the corresponding abstract event.

(REF3) $\text{I}(x) \wedge \text{J}(x, y) \wedge \text{BAC}(y, y') \Rightarrow \text{J}(x, y') :$

The invariant in the refinement model is preserved by the refined event but the event of the refinement model is a new event which was not visible in the abstract model; the new event refines *skip*.

Proof obligations for refinement

(REF4): $I(x) \wedge J(x, y) \wedge (G_1(x) \vee \dots \vee G_n(x)) \Rightarrow H_1(y) \vee \dots \vee H_k(y) :$

The guards of events in the refinement model are strengthened and we have to prove that the refinement model is not more blocked than the abstract.

(REF5): $I(x) \wedge J(x, y) \Rightarrow V(y) \in \mathbb{N}$

(REF6): $I(x) \wedge J(x, y) \wedge BAC(y, y') \Rightarrow V(y') < V(y) :$

New events should not block forever abstract ones.

(REF7): $\Gamma(s, c) \vdash I(x) \wedge J(x, y) \wedge \text{grd}(E) \Rightarrow \exists y' \cdot P(y, y')$

Refining the factorial model

```
REFINEMENT RFACT
REFINES FACTORIAL_EVENTS
VARIABLES  fac,result,m
INVARIANT
  fac : NATURAL +-> NATURAL & fac <: factorial &
  dom(fac) <: 0..m & dom(fac) /= {}
VARIANT n-x
INITIALISATION x:=0 || fac:={0|->1}
EVENTS
prog = SELECT p /: dom(fac) THEN
  ANY x WHERE
    x:NATURAL & x : dom(fac) & x+1 /: dom(fac)
  THEN
    fac(x+1) := (x+1)*fac(x)
  END
END;
computation = SELECT p : dom(fac) THEN  result:=fac(p)  END
END
```

The factorial model

MODEL

FACTORIAL_EVENTS

CONSTANTS *factorial, m*

PROPERTIES

$$\begin{aligned} & m \in \mathbb{N} \wedge \text{factorial} \in \mathbb{N} \leftrightarrow \mathbb{N} \wedge 0 \mapsto 1 \in \text{factorial} \wedge \\ & \forall (n, fn). (n \mapsto fn \in \text{factorial} \Rightarrow n+1 \mapsto (n+1) \cdot fn \in \text{factorial}) \wedge \\ & \forall f \cdot \left(\begin{array}{l} f \in \mathbb{N} \leftrightarrow \mathbb{N} \wedge \\ 0 \mapsto 1 \in f \wedge \\ \forall (n, fn). (n \mapsto fn \in f \Rightarrow n+1 \mapsto (n+1) \times fn \in f) \\ \Rightarrow \\ \text{factorial} \subseteq f \end{array} \right) \end{aligned}$$

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INITIALISATION

result := $\in \mathbb{N}$

EVENTS

computation = **begin** *result* := *factorial*(*m*) **end**

END

Summary on the B modelling language

- A language for expressing mathematical structures: sets, relations, functions, ...
 - A language for expressing transitions over states: events
 - A language for expressing safety properties
 - A language of system models
 - And more ... like modalities
 - **Next session: case studies**
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